

[10191/1957]

A METHOD AND A PLAYBACK DEVICE FOR PERFORMING A TRACK SKIP  
METHOD FOR PERFORMING A TRACK SKIP AND A PLAYBACK DEVICE

Background Information

The present invention starts from a method for performing a track skip (operation) according to the species defined in independent Claim 1 and from a playback device according to the species defined in independent Claim 4.

A control system for a read device of a disk player is already known from GB 2 228 132 A. In this context, the position data representing the present position of a read device are read from a disk. The distance of the present position to the starting position of the read device is calculated according to the read position data. The read device is moved to the starting position in accordance with the calculated distance. For this purpose, the time necessary for moving the read device, for triggering a transport motor for the read device is determined from the calculated distance. Subsequently, the read device is moved for the calculated time.

Summary of the Invention

In contrast, the method according to the present invention and having the features of independent Claim 1 and the playback device according to the present invention and having the features of independent Claim 4 have the advantage that no position data must be read out from the storage disk for a track skip; so that it is also possible to skip a track in a state in which the storage disk is not being moved and no position data can be read out. This can be the starting state, for example. In this manner, the result is a quicker access time to the selected track from the non-moving state, e.g. when starting the storage disk. Since no position data needs to be read from the storage disk for a track skip, it is not necessary for the entire track skipping operation to move the

storage disk or to set it in rotation. In this manner, energy is saved. The time necessary for accelerating the storage disk to a rotational speed at which the position data could be read out from the storage disk is also saved.

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Advantageous further refinements and improvements of the method specified in independent Claim 1 and of the playback device specified in independent Claim 4 are made possible by the measures indicated in the dependent claims.

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It is particularly advantageous that the determined time is multiplied by an adjustable correction factor, and that the read device is moved in the direction of the selected track for the time corrected in this manner. Changes in the ease of movement of the read device can be compensated for in this manner in that the correction factor is adjusted to the changes in the ease of movement of the read device.

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A further advantage is that, after completion of the track skip, position data read out by the read device are compared to position data known for the selected track, and that the correction factor is adjusted as a function of a difference between the read-out and the known position data. In this manner, the correction factor is automatically adapted to the ease of movement of the read device. The resulting self-learning effect results in the track skips of the read device being carried out with increasing accuracy over time, thereby causing an automatic optimization of the skip times of the read device calculated for the track skips.

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#### Brief Description of the Drawings

An exemplary embodiment of the present invention is represented in the drawing and explained in detail in the following description. Figure 1 shows a block diagram of a playback device according to the present invention; Figure 2 shows a detail of the block diagram according to Figure 1; and

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Figure 3 shows a flow chart for a control of the playback device according to the present invention.

#### Description of the Exemplary Embodiment

5 In Figure 1, 10 designates a playback device for optical storage disks, configured as a compact disk player, for example. Playback device 10 includes a drive motor 1 for driving an optical storage disk 14 inserted in playback device 10 and configured as a compact disk, for example, in a rotary  
10 manner via a shaft 45. In accordance with a double arrow represented in Figure 1, a read device 2 is guided via a positioning device 35 in a radial direction, along a surface of optical storage disk 15. Read device 2 is connected via a detection unit 3 and a signal-processing unit 4 to a control  
15 unit 6. Detection unit 3, signal processing unit 4, and control unit 6 are each connected to a servo unit 5. An input and display unit 8 is connected to control unit 6. Servo unit 5 drives drive motor 1, positioning device 35, and read device 2. Furthermore, a switch 40 is provided that is situated in  
20 the vicinity of a starting position 25 of a lead-in area 20 of optical storage disk 15 according to Figure 2. Switch 40 is likewise connected to control unit 6.

Storage disk 15 includes three regions: a lead-in area 20, in  
25 which a table of contents designated as TOC is recorded, a program area 50, in which the useful data, e.g. music signals, are recorded, and an end area 55, in which a program termination signal is recorded. These three areas are situated on storage disk 15 in the described sequence, i.e., in a  
30 radial direction from shaft 45 on the inside of storage disk 15 toward the outside. This means that lead-in area 20 is the most inner region, end area 55 is the most outer region of optical storage disk 15, and program area 50 is between lead-in area 20 and end area 55. Stored in the table of contents of  
35 lead-in area 20 are, for example, the number of program data, e.g. of music titles recorded on a compact disk, the addresses

or starting positions of the program data on storage disk 15,  
and the total playback time of all of the program data  
recorded on storage disk 15. In this context, the content data  
can be recorded repeatedly in lead-in area 20 of storage disk  
5 15 to the starting position of program area 50. The useful  
data, e.g. the music data in the case of a compact disk,  
recorded in program area 50 include a plurality of frames.  
Every frame includes a synchronization signal, a subcode of-  
control data, data bits of useful signals, e.g. music signals  
10 and error correction bits for correcting errors in the data  
bits. The subcodes also include address data.

Read device 2 optically reads out the data recorded on storage  
disk 15 and optoelectrically converts the read signals. The  
15 electrical recording signal obtained in this manner is  
supplied to detection unit 3. From there, the recording signal  
is relayed to signal processing unit 4. Detection unit 3 also  
delivers error signals, e.g. a focus error signal and a track  
error signal, to servo unit 5. In signal processing unit 4,  
20 the recording signal is converted into a digital signal in  
order to detect the synchronization signal, to demodulate the  
useful data signal, i.e., the music signal in this example,  
and to detect the subcode. The useful information signal or  
the music signal undergoes a digital-to-analog conversion, so  
25 that it can be emitted as an analog audio signal at an output  
60 of signal processing unit 4. Part of the synchronization  
signal is transmitted by signal processing unit 4 to servo  
unit 5, and the subcode is relayed by signal processing unit 4  
to control unit 6.

30 In response to the error signal from detection unit 3, to the  
synchronization signal of signal processing unit 4, and to  
control signals of control unit 6, servo unit 5 emits servo  
signals for a focus servomechanism, a track servomechanism,  
35 and a positioning device 35. In this context, in the case of  
the focus servomechanism, a focus coil of read device 2 is

driven in such a manner that a light beam 70 from read device 2 is focused on a reflective surface of storage disk 15.

Accordingly, in the case of the track servomechanism, a track coil of read device 2 is driven such that light beam 70 is directed at a track to be read out. Accordingly, a transport (carriage) motor 65 of positioning device 35 is driven such that read device 2 is moved in a radial direction along the surface of storage disk 15. Finally, servo unit 5 also emits servo signals for a CLV servomechanism (constant linear velocity), which linearly drives drive motor 1 at a constant speed.

Control unit 6 is configured as a microcomputer that emits the control signal for controlling the different units of playback device 10 described above.

Input/display unit 8 can also only be configured as an input unit and enables the input of an address of a data group of a storage disk 15 inserted into playback device 10. For example, this can be the initial address of a music title. In this context, the initial address of a title can be input at a numeric keypad of input/display unit 8, using the title number. When reading out the table of contents in lead-in area 20 for the first time, the content data are stored in a memory not shown in Figure 1, the memory being assigned to control unit 6 and being integrated in it or connected to it. In this context, the memory can also be situated outside of playback device 10 and is then to be connected to playback device 10 or control unit 6 of playback device 10 via a suitable interface. By comparing the title number input at input/display unit 8 to the content data stored in the memory, control unit 6 can be used to select a desired destination address to which read device 2 or light beam 70 of read device 2 is to be moved on storage disk 15. From this destination address, a selected track 30 can be determined in control unit 6, whose position data on storage disk 15 are known in the form of the

destination address and are stored in the memory via the content data.

The data of storage disk 15 are recorded in a spiral. However,  
5 due to the track width and the minimal rise of the spiral, one refers to individual tracks, so that one can imagine the data recorded in concentric rings on storage disk 15. There are two possibilities to change from track to track. On the one hand, there is positioning device 35 as a roughly adjusting unit on  
10 which read device 2 including an optical scanning unit (not shown), which generates light beam 70 for optically scanning the data recorded on storage disk 15, is located. With the aid of transport motor 65 of positioning device 35, read device 2 is moved in a radial direction across the surface of storage  
15 disk 15. A unit for fine adjustment is configured as a lens of the optical scanning unit that is suspended in a free-moving manner in a magnetic field. In this context, this lens (also not shown in the figures) can be moved in a direction perpendicular to storage disk 15 via the focus servomechanism  
20 or in accordance with the driving of the focus coil of the focus servomechanism that affects this magnetic field. Moreover, the lens of the optical scanning unit can be moved in a direction perpendicular to the tracks by accordingly driving the track coil of the track servomechanism, which also  
25 influences this magnetic field. As such, an area of approximately 600 tracks is currently covered.

If a skip from a currently scanned track on storage disk 15 to, for example, a track 30 selected at input/display unit 8  
30 in program area 50 of storage disk 15 is demanded, the number of tracks to be skipped is calculated from the difference of the current track and selected track 30. Currently, drive motor 1 of playback devices 10 configured as a compact disk player and for reproducing music operates as a function of the  
35 position of read device 2 in the radial direction along the surface of-storage disk 15 and as a function of the total

playing time of storage disk 15 at a rotational speed of between approximately 3.3 rotations per second and approximately 4.5 rotations per second, for example. This rotational speed limits the controllable, translatory speed of read device 2 in the radial direction, along the surface of storage disk 15, since for counting the tracks, light beam 70 must be on the data tracks for a minimum time in order to read out the corresponding information from the data tracks. This results in an upper translatory speed limit. Furthermore, a minimum rotational speed of storage disk 15 is necessary for scanning and reading out the data tracks via light beam 70, so that there is also a lower speed limit of storage disk 15, starting from which the tracks can first be counted. This is particularly useful when upon beginning the playback operation of storage disk 15, i.e., upon increasing the rotational speed of storage disk 15 from zero to the lower speed limit, a skip is to be made to a selected track 30. In this case, the access time to the selected track is delayed by the time until reaching the minimum speed limit. According to the present invention, this delay is circumvented in that a controllable displacement of read device 2 in a radial direction along the surface of storage disk 15 is described that does not require the evaluation or scanning of information recorded in the data tracks. The same difficulty also arises in pause situations in which at least drive motor 1 is inactive to reduce power loss. Also in this case, storage disk 15 must first be brought to a specific minimum rotational speed determined by the lower speed limit before the tracks can begin to be counted, thereby extending the effective access time to selected track 30.

Thus, in accordance with the present invention, it is proposed to calculate the distance to be covered from the current track to selected track 30 on the basis of the time necessary for the track skip of read device 10, and not on the basis of the number of tracks. In this context, the method proceeds as follows: In response to a user requesting a track skip, e.g.

by an appropriate input at input/display unit 8, from the track currently scanned by light beam 70 to a track 30 also selected, for example, at input-display unit 8, e.g. in the form of title number information and representing, for this selected example, the initial address of the selected title or of a selected data group, read device 2 is moved by positioning device 35, which is accordingly driven by control unit 6, in the direction of lead-in area 20 of storage disk 15 until switch 40 is actuated in accordance with Figure 2, i.e., is brought from a first switch position represented by a dotted line in Figure 2 into a second switch position, which, according to the example in Figure 2, is characterized in that a switching contact 75 is contacted. By closing a corresponding electric circuit, the actuation of switch 40 is detected in control unit 6. In this context, light beam 70 of read device 2 is in starting position 25 of lead-in area 20 of optical storage disk 15 according to Figure 2, in which the same reference numerals designate the same elements as in Figure 1. Control unit 6 determines from selected track 30 the time necessary for the track skip from starting position 25 to this selected track 30. In this context, a standard turn-on time for the movement of read device 2 via positioning device 35 is first calculated for the track skip from starting position 25 to selected track 30, the time being multiplied by a correction factor known from the previous skips if necessary. In this context, for the calculation of the standard turn-on time, a previously determined quotient of the time necessary for skipping a number of tracks and of this number of tracks is determined and is multiplied by the number of tracks to be skipped resulting from the difference between selected track 30 and starting position 25. This yields the duration of the motor drive pulse necessary for driving transport motor 65 in order to radially move read device 2 via positioning device 35 by the desired number of tracks, along the surface of storage disk 15, in the direction of selected track 30. In this context, control unit 6 supplies the



corresponding motor drive pulse having the determined,  
required time duration to transport motor 65. By correcting  
the skip time determined by control unit 6 using an adjustable  
correction factor, changes in the ease of movement of read  
5 device 2 as well as the fact that starting position 25 can  
generally only be maintained approximately within lead-in area  
20 can be compensated for in that the correction factor is  
accordingly adjusted. Positioning device 35 then moves read  
device 2 for the time corrected in this manner in the  
10 direction of selected track 30. In this context, the  
correction factor can be adjusted in that, after completion of  
the track skip, control unit 6 compares position data read out  
by read device 2 to the position data known for selected track  
30, and in that control unit 6 adjusts the correction factor  
15 as a function of the difference between the read-out and the  
known position data. In this manner, the difference between  
the read-out and the known position data can be continuously  
reduced in further track skips, so that a self-learning effect  
is achieved in which the system learns over time to perform  
20 the skips with increasing accuracy. Thus, it is possible to  
automatically optimize the accuracy of the track skips over  
time via the adjustable correction factor that can be adapted  
to external conditions. The rotational speed of storage disk  
15 having at least reached the lower speed limit is naturally  
25 a prerequisite for reading out the position data after  
completion of the track-skip.

Of course, the method according to the present invention can  
be combined with already known methods in which track skips  
30 are performed on the basis of read-out position data of the  
current track, it being necessary in these methods to  
presuppose a rotational speed for storage disk 15 that is  
above the required, already described lower speed limit.

35 However, as a result of the method according to the present  
invention, the time duration of a track skip is also not

affected by the described upper translatory speed limit, since no position data have to be read out for the track skip itself.

5 The ease of movement of read device 2 can be changed, for example, by external influences, such as temperature, wear, etc.

10 A flow chart for the functioning method of control unit 6 is represented in Figure 3. At a program point 100, a check is made to determine whether switch 40 was operated. If this is the case, the program branches to program point 110, otherwise the program branches to program point 105. At program point 105, control unit 6 causes transport motor 65 of positioning  
15 device 35 to move read device 2 to the inside of storage disk 15, in the direction of shaft 45. The program subsequently branches back to program point 100. At program point 110, control unit 6 calculates the required skip time for read device 2 to reach selected track 30. At program point 115,  
20 control unit 6 multiplies the time calculated at program point 110 by the correction factor. At program point 120, via a motor drive pulse, control unit 6 causes transport motor 65 of positioning device 35 to move read device 2 in the direction of selected track 30 for the time period corrected at program  
25 point 115. At program point 125, the track skip is ended, and light beam 70 of read device 2 focuses on the track reached at the end of this track skip. Control unit 6 compares the position information read out by read device 2 from the track reached at the end of the track skip to the position data  
30 known for selected track 30 and adjusts the correction factor as a function of the difference between the read-out and the known position data such that a multiplication of the skip time determined at program point 110 and the correction factor newly adjusted at program point 125 results in a skip time in  
35 which a track skip of read device 2 from starting position 25 in the direction of selected track 30 would have resulted in

light beam 70 focusing on selected track 30. After program point 125, the program segment is exited.

5 The correction factor current in each case and the standard turn-on time can also be stored in the memory not shown in the figures or in another manner. The memory can be configured as a write-read memory, for example.

10 As already described, for the readout operation from storage disk 15 presupposed in the adaptation of the correction factor at program point 125, at least one rotational speed of storage disk 15 corresponding to the lower speed limit is necessary, for which purpose control unit 6 is to accordingly drive drive motor 1 at program point 125 at the latest. If the rotational  
15 speed of storage disk 15 is not yet in the required speed range at program point 125, light beam 70 is to be focused on the track reached at the end of the track skip until it is possible to read out the position data of this track and, thus, to adapt the correction factor.

20 To not lose time above all after pause situations or when initiating playback of storage disk 15, control unit 6 should induce the increase in the rotational speed of storage disk 15 at the same time as the introduction of the track skip, so  
25 that the rotational speed of storage disk 15 is already in the speed range necessary for reading out position data at the conclusion of the track skip.

30 The method according to the present invention can be used for any optical storage disk 15, e.g. also for CD ROMs. The same is true for playback device 10, which is not limited to compact disk players, but can be generally configured as a playback device for optical storage disks, i.e., also as a CD ROM drive, for example.